



MX Series I/O Modules



The MX4-R2 expansion module provides temperature and frequency input capability to the C5 and future generations of FW Murphy Controllers using CAN proprietary communication with enhanced diagnostics. The MX5-R2 expansion module provides input/output capability to the C5 generation and future generations of FW Murphy Controllers using CAN proprietary communications with enhanced diagnostics.

- Dedicated I/O expansion modules
- Various models available to I/O requirements
- Communications via CAN with Centurion™ controller
- Type J or K Thermocouples or 100Ω Pt 3-wire RTD temperature measurement
- B+ or B- Digital inputs
- Low Voltage Digital outputs (sinking)
- 0-5V or End-of-Line 0-25mA Analog inputs
- DIN Rail Mountable
- Approved Certification:
 - Class I, Div 2, Grps A, B, C, D Haz. Loc. T4
 - Class I, Zone 2, AEx ec [ic] IIC T4 Gc, Ex ec [ic] IIC T4 Gc X
 - ATEX Zone 2
 - IECEx Zone 2

Overview

The MX4-R2 expansion module provides temperature and frequency input capability to the C5 and future generations of FW Murphy Controllers using CAN proprietary communication with enhanced diagnostics. Serial RS-485 port and 2 Ethernet ports also provide other communication methods to work with any Modbus RTU or Modbus TCP/IP client device. The MX4-R2 module features 18 thermocouple / 9 RTD inputs and 1 magnetic pickup input. MX4-R2 is backward compatible to MX4.

The MX5-R2 expansion module provides input/output capability to the C5 generation and future generations of FW Murphy Controllers using CAN proprietary communications with enhanced diagnostics. Serial RS-232 or RS-485 ports and 2 Ethernet ports also provide other communication methods to work with any Modbus RTU or Modbus TCP/IP client device. The MX5-R2 module features 24 Digital inputs, 16 Digital outputs, 10 Analog inputs, 4 Analog outputs and 1 magnetic pickup input. MX5-R2 is backward compatible to all models of the MX5.

Any combination of MX-Series modules can be added to enable Digital and Analog I/O and Temperature inputs for communication and monitoring by the master controller.

Specifications

MX4-R2 Expansion I/O Module

- Operating Temperature: -40° to 185° F (-40° to 85° C)
- Power input: 14.1 W max 10-30 VDC
- Configuration: PC-based Centurion Configuration Software
- 18* thermocouple inputs:
 - J or K Type thermocouples (ungrounded)
 - 9* 3-wire 100Ω Pt RTD temperature inputs***
 - Open, short DC-, Short DC+ wire fault detection
 - Cold junction compensation

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FW MURPHY®
PRODUCTION CONTROLS



Official FW Murphy Distributor
PT. ATAMORA TEHNIK MAKMUR

MX Series I/O Modules

- One magnetic pickup input* / AC Run Signal: 4.5 VAC – 120 VAC, 30 Hz – 10 kHz
- Third-party approvals for MX4-R2:
 - Class I, Div 2, Grps A, B, C, D Haz. Loc. T4
 - Class I, Zone 2, AEx ec [ic] IIC T4 Gc, Ex ec [ic] IIC T4 Gc X
 - ATEX Zone 2
 - II 3G Ex ec [ic] IIC T4 Gc
 - DEMKO 18 ATEX 1926X
 - -40°C < Tamb < +85°C
 - IECEx Zone 2
 - Ex ec [ic] IIC T4 Gc
 - IECEx UL 18.0072X
 - -40°C < Tamb < +85°C

MX5-R2 Expansion I/O Module

- Operating temperature: -40° to 185° F (-40° to 85° C)
- Power input: 16.5 W max 10-30 VDC
- Configuration: PC-based Centurion Configuration Software
- 24^{***} Digital inputs:
 - NO or NC (active high/active low) intrinsically safe
 - Optically isolated DC digital inputs (active high/active low) with LED indicators
 - Polarity sense / wire fault detection on normally closed systems
 - Approved for use with general purpose switches in hazardous areas
- 10* analog inputs: 0-24 mA or 0-5 VDC, 15 bit hardware.
- 6 std. config./ 16^{***} digital outputs: FET (sink)
- 4 analog outputs: 4-20 mA, 16 bit hardware
- 1 magnetic pickup input* /AC Run Signal: 4.5 VAC -120 VAC, 30 Hz to 10 kHz
- Third-party approvals for MX5-R2:
 - Class 1, Div 2, Grps A, B, C, D haz. Loc. T4
 - Class 1, Zone 2, AEx ec [ic] IIC T4 Gc, Ex ec [ic] IIC T4 Gc X
 - ATEX Zone 2
 - II 3G Ex ec [ic] IIC T4 Gc
 - DEMKO 18 ATEX 1926X
 - -40°C < Tamb < +85°C
 - IECEx Zone 2
 - Ex ec [ic] IIC T4 Gc X
 - IECEx UL 18.0072X
 - -40°C < Tamb < +85°C

* Non-incendive (Digital Inputs, Analog Inputs and Temperature Inputs are intrinsically safe and non-incendive).

**Applies only to Centurion Custom and Rockwell Automation Processor Configurations.

*** RTD=Resistive Temperature Device, American RTD Standard, TCR 0.00392, units Ohms/Ohm / deg. between 0-100 C.

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OPERATION OFFICE

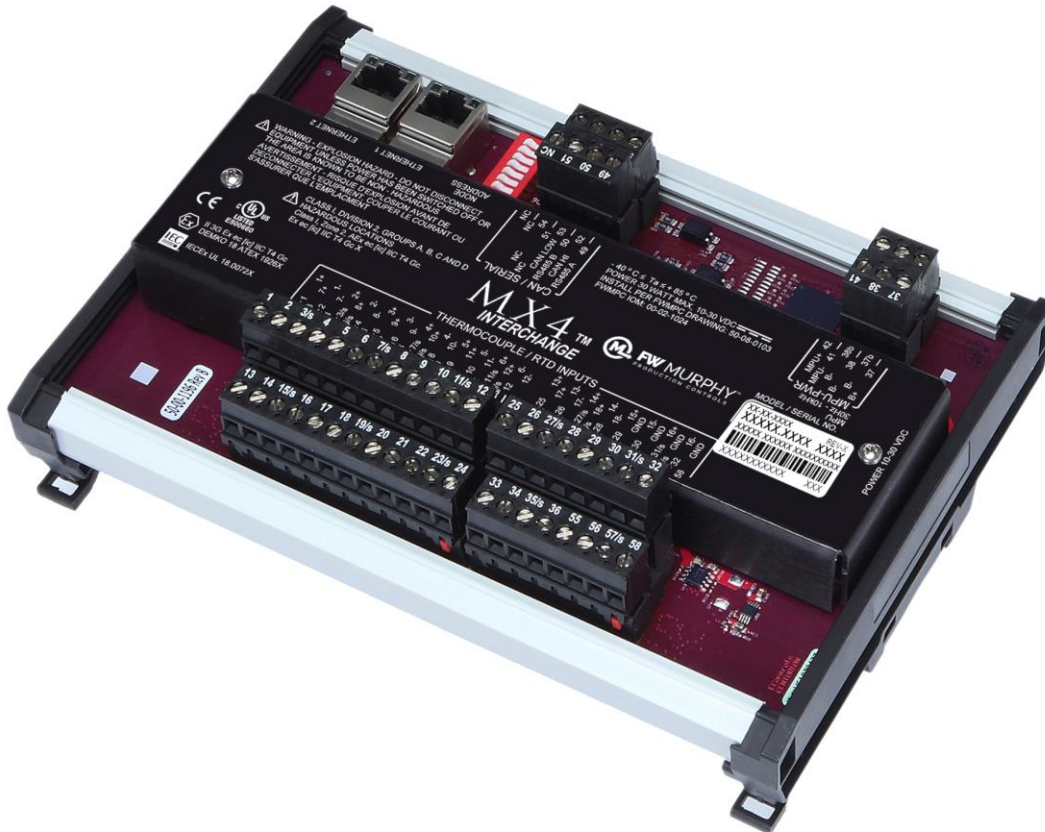
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Interchange™ Comm Control Module, MX4-R2 Series

Installation and Operations Manual

For Models with Date Codes S8 or Higher

Warranty - A limited warranty on materials and workmanship is given with this FW Murphy product.
A copy of the warranty may be viewed or printed by going to <http://www.fwmurphy.com/warranty>



**BEFORE BEGINNING INSTALLATION OF THIS FW MURPHY
PRODUCT:**

- Please read the following information before installing the MX4-R2 Module. This installation information is intended for MX4-R2 Module only.
- Visually inspect the product for any damage during shipping.
- Before proceeding please visit our website and review our support documentation including Wiring the Murphy Way
www.fwmurphy.com/uploaded/WIR_Murphy_Way.pdf
- Disconnect all power and be sure machine is inoperative before beginning installation.
- Installation is to be done only by a qualified technician of the Responsible Body.
- Observe all Warnings and Cautions at each section in these instructions.
- Device shall be wired in accordance with NEC, CEC or other local code, as applicable.
- Please contact FW Murphy immediately if you have any questions.

For Class I, Division 2:

THIS EQUIPMENT IS AN OPEN-TYPE DEVICE AND IS MEANT TO BE INSTALLED IN AN ENCLOSURE SUITABLE FOR THE ENVIRONMENT SUCH THAT THE EQUIPMENT IS ONLY ACCESSIBLE WITH THE USE OF A TOOL.

THIS EQUIPMENT IS SUITABLE FOR USE IN CLASS I, DIVISION 2, GROUPS A, B, C AND D OR NON-HAZARDOUS LOCATIONS ONLY.

WARNING – EXPLOSION HAZARD – DO NOT DISCONNECT EQUIPMENT UNLESS POWER HAS BEEN REMOVED OR THE AREA IS KNOWN TO BE NON-HAZARDOUS.

WARNING – EXPLOSION HAZARD – DO NOT REPLACE BATTERIES UNLESS THE AREA IS KNOWN TO BE FREE OF IGNITABLE CONCENTRATIONS.

TEMPERATURE CODE OF T4 FOR ALL MODELS.

PROVIDES NONINCENDIVE FIELD WIRING OUTPUTS/INPUTS WHEN WIRED ACCORDING TO DRAWING 50-08-0103 (MX4-R2-X).

For AEX/EX Class I, Zone 2:

THE EQUIPMENT SHALL ONLY BE USED IN AN AREA OF POLLUTION DEGREE 2.

THE EQUIPMENT SHALL BE INSTALLED COMPLETELY WITHIN AN ENCLOSURE THAT PROVIDES A MINIMUM INGRESS PROTECTION OF IP 54 IN ACCORDANCE WITH UL60079-0 AND ONLY ACCESSIBLE BY THE USE OF A TOOL.

THE WIRE SIZE, TORQUE RATING OF 12-24 AWG, 0.37-0.44 ft. lbs.(0.4-0.5 Nm), AND SUITABLE SUPPLY WIRE TEMPERATURE RATING OF 97°C MINIMUM SHALL BE PROVIDED FOR THE INPUT POWER TERMINAL BLOCK.

ALL MARKING INFORMATION EXCEPT FOR SERIAL NUMBER/DATE CODES SHALL BE REPEATED.

PROVIDES NONINCENDIVE FIELD WIRING OUTPUTS/INPUTS WHEN WIRED ACCORDING TO DRAWING 50-08-0103 (MX4-R2-X).

SPECIAL CONDITIONS FOR USE IECEx/ATEX Zone 2:

THE EQUIPMENT SHALL ONLY BE USED IN AN AREA OF NOT MORE THAN POLLUTION DEGREE 2, AS DEFINED IN IEC/EN 60664-1.

THE EQUIPMENT SHALL BE INSTALLED IN AN ENCLOSURE THAT PROVIDES A DEGREE OF PROTECTION NOT LESS THAN IP 54 IN ACCORDANCE WITH IEC/EN 60079-0 AND ONLY ACCESSIBLE BY THE USE OF A TOOL.

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Table of Contents

FW Murphy Interchange Comm Control Module Series	1
Accessories.....	1
Specifications.....	1
Power input: 14.1 W max 10-30 VDC	1
Installation	2
Dimensions	2
Install MX4-R2 Module	3
Wire Connections	4
Wire Diagram — MX4-R2 Module.....	4
Entity Parameters.....	5
Thermocouple / RTD Inputs (Pins 1 – 36 and 55 – 58)	8
Power (Pins 37 – 38).....	9
Magnetic Pickup, MPU (Pins 41 – 42).....	10
RS485 (Pins 49 – 50).....	11
CAN (Pins 52 – 53)	13
DIP Switch Configuration	14
Ethernet.....	15
Controller Operating Properly (COP) LED Codes	17
Communications for Standard IO Application Mode (default)	18
Communications for Rockwell Automation IO Mode (optional)	19
Modbus Holding Register Description (Standard IO Application Mode)	20

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FW Murphy Interchange Comm Control Module Series

The MX4-R2 expansion module provides temperature and frequency input capability to the Centurion and future generations of FW Murphy Controllers using CAN proprietary communication with enhanced diagnostics. A serial RS485 port and 2 Ethernet ports also provide communication methods to work with any Modbus RTU or TCP/IP client device. MX4-R2 is backward compatible to MX4. Load Rockwell IO Application for EtherNet/IP (CIP) Protocol function.


Accessories

MX4-R2 Plug Kit (00032656) Printed Terminal Plugs for MX4-R2 Expansion I/O Module

Specifications

- Operating temperature: -40° to 185° F (-40° to 85° C)

Power input: 14.1 W max 10-30 VDC

- All input options individually software selectable. No jumpers required.
- 18* Thermocouple temperature inputs:
 - J or K Type Thermocouples (ungrounded)
 - 9* 3-wire 100Ω Pt RTD temperature inputs**
 - Cold junction compensation
 - Open, short DC-, short DC+ wire fault detection
- One magnetic pickup input*/AC run signal
 - 30 to 10 kHz
- 4 Communication ports:
 - SERIAL RS485
 - Protocol: MODBUS RTU (server)
 - CAN
 - Protocol: Proprietary for FW Murphy hardware
 - Two Ethernet 10/100 (DLR), Single MAC ID:
 - Protocol: Modbus TCP/IP (server) standard or Ethernet/IP (CIP) in Rockwell IO Application Mode
- Third-party approvals for MX4-R2:
 - Class I, Div 2, Grps A,B,C,D Haz. Loc. T4
 - Class I, Zone 2, AEx ec [ic] IIC T4 Gc
Ex ec [ic] IIC T4 Gc X
 - ATEX Zone 2:
 -  II 3G Ex ec [ic] IIC T4 Gc
 - DEMKO 18 ATEX 1926X
 - -40°C ≤ Tamb ≤ +85°C
 - IECEX Zone 2:
 - Ex ec [ic] IIC T4 Gc
 - IECEX UL 18.0072X
 - -40°C ≤ Tamb ≤ +85°C

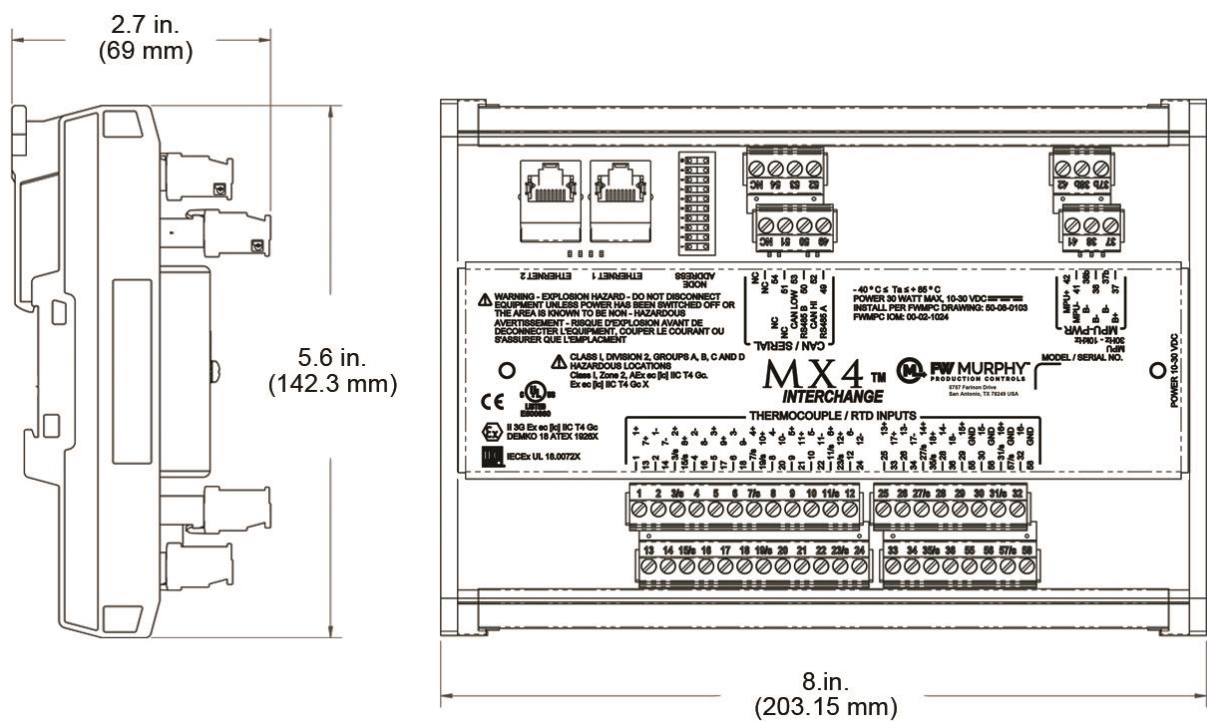
* Non-incendive. Temperature Inputs are intrinsically safe and non-incendive.

** RTD=Resistive Temperature Device, American RTD Standard, TCR 0.00392, units Ohms/Ohm / deg. between 0-100 C.

NOTE: For each channel that is selected as RTD, 2 thermocouple channels are used and no longer available as thermocouple channels.

Installation

Dimensions



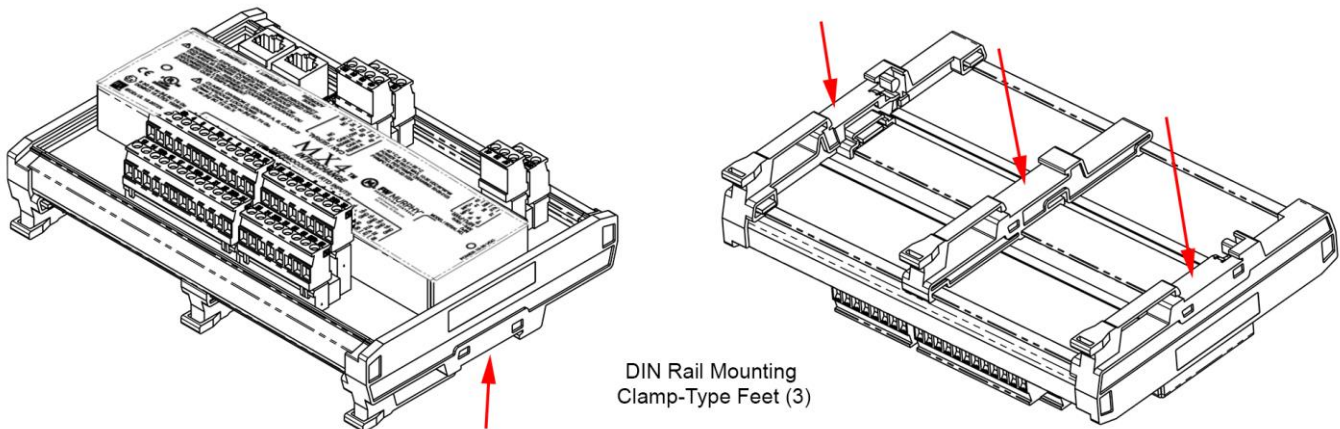
Install MX4-R2 Module

The MX4-R2 must be mounted in an enclosure meeting the requirements of IP54 or greater according to the intended use and environmental conditions in accordance with standard UL and only accessible by use of a tool.

NOTE: IP requirement is ONLY for North America and IECEx/ATEX Zones UL 60079, IEC/EN 60079-0.

- Operating Temperature -40° to 185° F (-40° C to +85° C)
- Pressure 80 kPa (0,8 bar) to 110 kPa (1,1 bar)
- Air with normal oxygen content, typically 21% v/v
- Temperature Class T4
- “ic”: intrinsic safety (for EPL Gc)
- Increased safety (for EPL Gc)

The MX4-R2 can be mounted vertically or horizontally on a standard DIN rail. Three clamp-type feet along the bottom of the controller attach to the DIN rail; however, rail stops are recommended to prevent sliding.



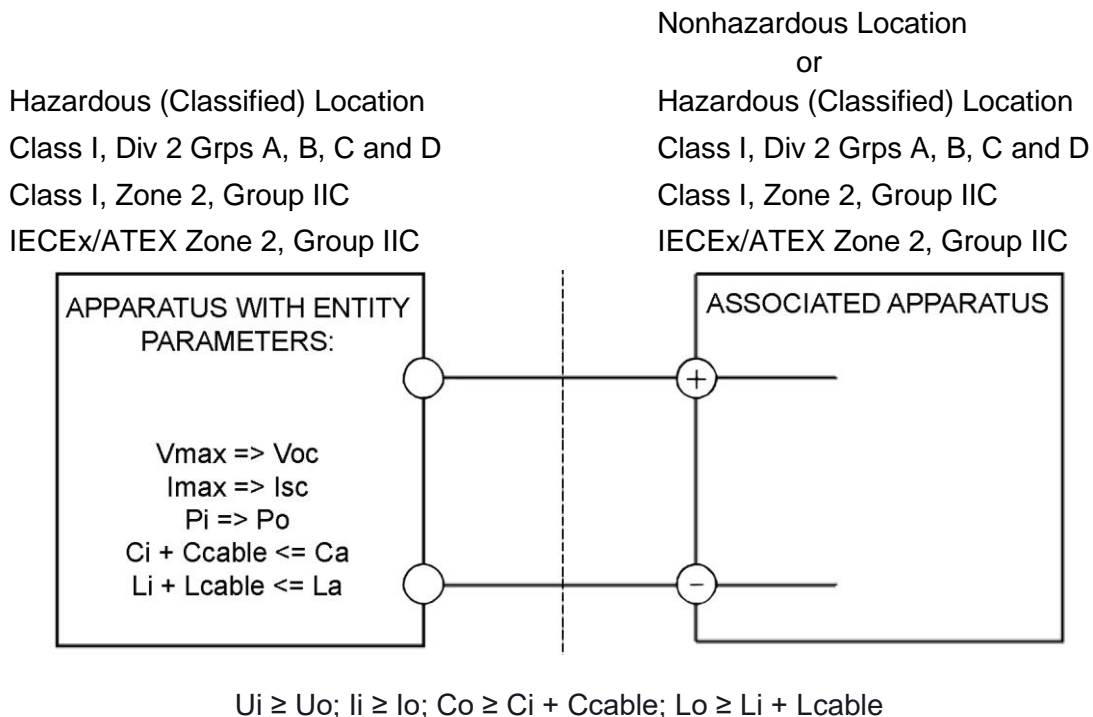
Wire Diagram — MX4-R2 Module



DO NOT SCALE DRAWING. DIMENSIONING AND TOLERANCING PER ASME Y14.5 - 2009 APPLY.	INCH 	 FW MURPHY PRODUCTION CONTROLS
DESCRIPTION WIRING DIAGRAM, MX4-R2		
REFERENCE 50080103 50080103, SI DIASM	PRODUCT NUMBER 50-08-0103 2-1 AND NOTED	REVISION 1 OF 3 C

Entity Parameters

1. The output current of this associated apparatus is limited by a resistor such that the output voltage-current plot is a straight line drawn between open-circuit voltage and short-circuit current. The Entity Concept allows interconnection of intrinsically safe apparatus with associated apparatus not specifically examined in combination as a system when the approved values of V_{oc} (or U_o) and I_{sc} (or I_o) for the associated apparatus are less than or equal to V_{max} (U_i) and I_{max} (I_i) for the intrinsically safe apparatus. Capacitance and inductance of the field wiring from the intrinsically safe equipment to the associated apparatus shall be calculated and must be included in the system calculations. Cable capacitance, C_{cable} , plus intrinsically safe equipment capacitance, C_i must be less than the marked capacitance, C_a (or C_o), shown on any associated apparatus used. The same applies for inductance (L_{cable} , L_i and L_a or L_o , respectively). Where the cable capacitance and inductance per foot are not known, the following values shall be used: $C_{cable} = 60 \text{ pF/ft.}$, $L_{cable} = 0.2 \text{ }\mu\text{H/ft.}$



2. This associated apparatus may also be connected to non-incendive or simple apparatus as defined in Article 504.2 and installed and temperature classified in accordance with Article 504.10 (B) of the National Electrical Code (ANSI/NFPA 70) or other local codes, as applicable. Examples of "simple apparatus" are general-purpose contact/switch, thermocouples and RTD.

3. For Intrinsically Safe devices selected associated apparatus must be third-party listed as providing intrinsically safe circuits for the application or have V_{oc} or V_t not exceeding V_{max} (or U_o not exceeding U_i), I_{sc} or I_t not exceeding I_{max} (or I_o not exceeding I_i), and the P_o of the associated apparatus must be less than or equal to the P_{max} or P_i of the intrinsically safe equipment. Examples of “simple apparatus” are general-purpose contact/switch, thermocouples and RTD.
4. Where multiple circuits extend from the same piece of associated apparatus, they must be installed in separate cables or in one cable having suitable insulation. Refer to Article 504.30(B) of the National Electrical Code (ANSI/NFPA 70) and Instrument Society of America Recommended Practice ISA RP12.6 for installing intrinsically safe equipment.
5. Intrinsically safe circuits must be wired and separated in accordance with Article 504.20 of the National Electrical Code (ANSI/NFPA 70) or other local codes, as applicable.
6. This associated apparatus has not been evaluated for use in combination with another associated apparatus.
7. Control equipment must not use or generate more than 250 V rms or dc with respect to earth.
8. For installations in which both the C_i and L_i of the intrinsically safe apparatus exceeds 1% of the C_o and L_o parameters of the associated apparatus (excluding the cable), then 50% of C_o and L_o parameters are applicable and shall not be exceeded.

**WARNING:**

EXPLOSION HAZARD - DO NOT DISCONNECT EQUIPMENT UNLESS POWER HAS BEEN SWITCHED OFF OR THE AREA IS KNOWN TO BE NON-HAZARDOUS.

AVERTISSEMENT - RISQUE D'EXPLOSION - AVANT DE DECONNECTER L'EQUIPEMENT, COUPER LE COURANT OU S'ASSURER QUE L'EMPLACEMENT EST DESIGNÉ NON DANGEREUX.

Entity Parameters (continued)

Thermocouple/RTD Inputs (Per Pin) J1-J2										
Designation	Uo[V]	Io[mA]	Po[mW]	Lo[H]	Co[μF]	Ui[V]	Ii[mA]	Pi[mW]	Li[mH]	Ci[μF]
Pins 2, 4, 6, 8, 10, 12, 14, 16, 18, 20, 22, 24, 26, 28, 30, 34, 36,	4.4	1.0	4.4	80	999.9	30	17.0	-	0	0.1
Pins 1, 3/s, 5, 7/s, 9, 11/s, 13, 15, 17, 19/s, 21, 23/s, 25, 27/s, 29, 31/s, 32, 33, 35/s	4.4	1.0	4.4	80	995.1	30	17.0	-	0.022	4.9
J2 Pin 55, 56, 57, 58	Thermocouple/RTD Inputs Ground									

RS485/CAN											
Designation	Uo[V]	Io[mA]	Po[mW]	Lo[mH]	Co[μF]	Ui[V]	Ii[mA]	Pi[mW]	Li[mH]	Ci[μF]	Ci[pF]
J4 RS485 Pins 49, 50	±5.0	±60	-	22.2	999.9	±12.0	±60	-	0	0.01	-
J4 RS485 Pin 51	Shield Connection Ground										
J4 CAN Pins 52, 653	±4.5	±5	-	3.2	999.9	±24	100	-	0	-	267
J4 CAN Pin 54	Shield Connection Ground										

MPU – Entity Parameters											
Designation	Type of Protection	Uo[V]	Io[mA]	Po[mW]	Lo[mH]	Co[μF]	Ui[V]	Ii[mA]	Pi[W]	Li[mH]	Ci[μF]
38b, 41 Pins	nA	-	-	-	0	0	-	-	-	-	-
42 Pin	nA	-	-	-	0.00075	-	40Vrms	0.001	0.12	-	-

Ethernet Per Port										
Designation	Uo[V]	Io[mA]	Po[mW]	Lo[mH]	Co[μF]	Ui[V]	Ii[mA]	Pi[mW]	Li[mH]	Ci[μF]
J5-J6	3.3	±61.5	-	21.2	999.9	3.3	±60	-	0	0.1

Thermocouple / RTD Inputs (Pins 1 – 36 and 55 – 58)

The MX4-R2 is equipped with 18 two-wire thermocouple and/or 9 three-wire RTD inputs.

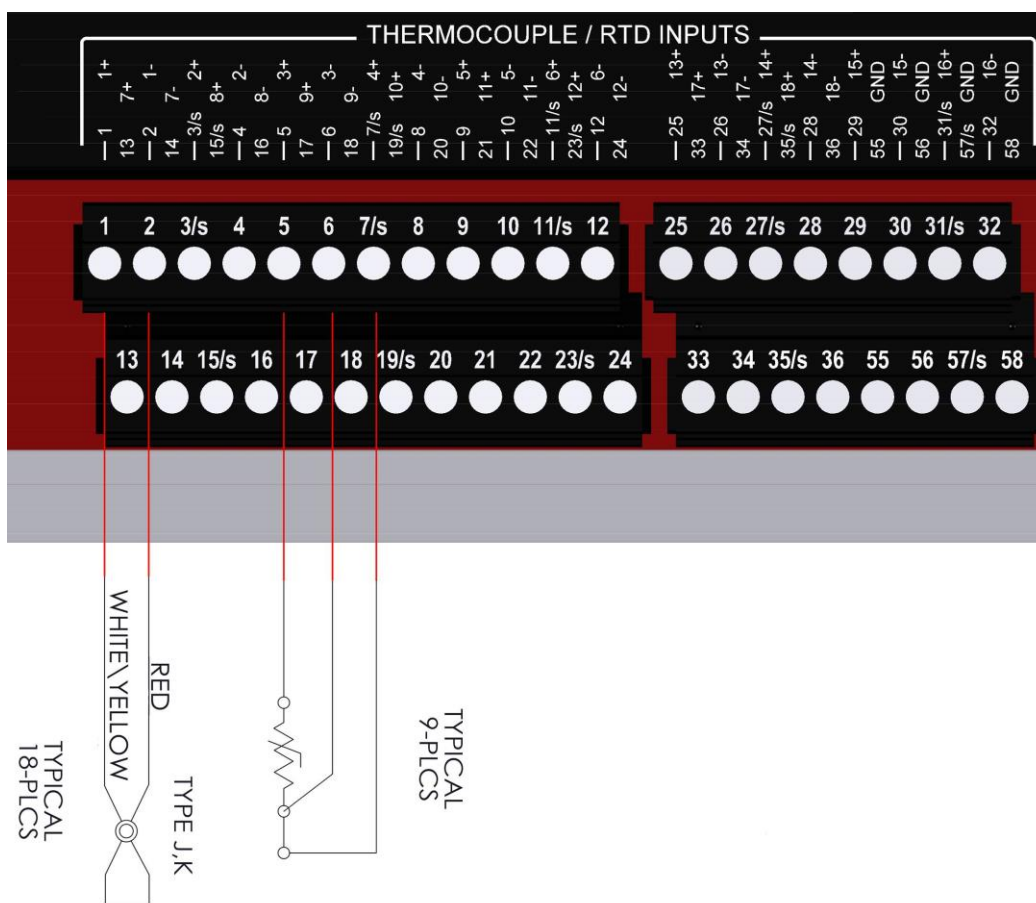
Thermocouples are wired using cover artwork labeled as + and -, such as 1+ and 1-. Thermocouples terminals can be seen labeled as 1 and 2 for TC 1 channel and 3 and 4 for TC 2 channel and so on. Use ungrounded thermocouples only, grounded thermocouples are not supported.

When RTD is selected for the channel, 3 terminals are required. RTDs are wired using cover artwork labeled with the same + and -, but also includes a /s for the sense lead. This terminal is also the + (plus) for the adjacent channel.

Therefore, the adjacent channel is no longer available as thermocouple and is disable.

RTD's terminals can be seen labeled in the as 1,2,3/s for the first channel and 5,6,7/s for the next channel and so on skipping the - (minus) terminal from the adjacent channel.

Important: For Entity Parameters or Power Supply and Grounding, refer to Wire Connections.

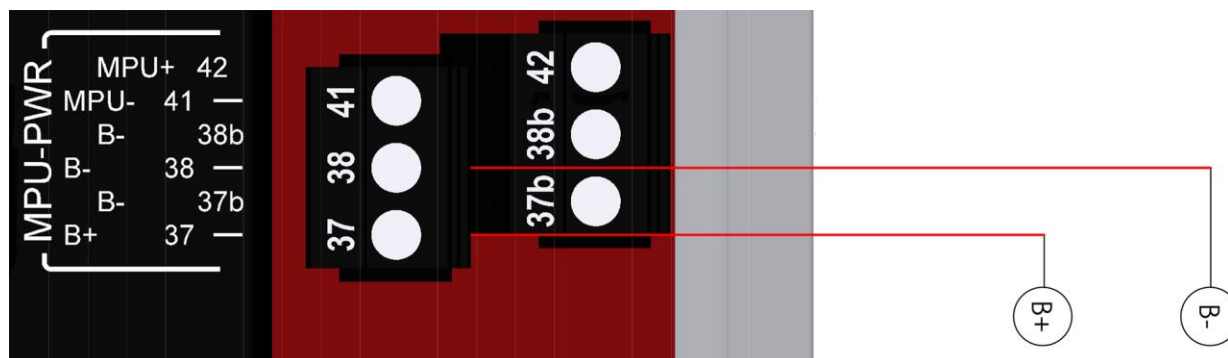


NOTE: These circuits are not required to be in conduit if all the requirements for ic protection are met and Authority Having Jurisdiction (AHJ) allows.

Power (Pins 37 – 38)

The 10-30 VDC power for the MX4-R2 is applied to the power supply terminals marked 37 B+ and 38 B-. An external 10-amp replaceable fuse protects the system from over-currents, and a power LED lights when power is applied to the system.

Important: For Entity Parameters or Power Supply and Grounding, refer to Wire Connections.



NOTE: Run power directly from battery posts to controller power terminals when battery is the power supply.

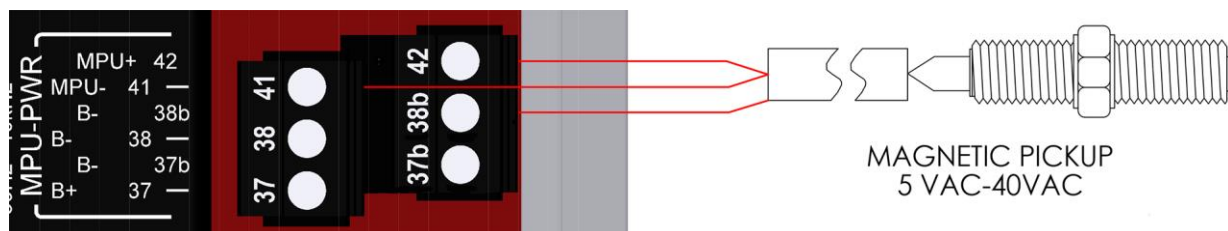
Maximum power ratings based on all I/O operating in the ON position with 10V supply. Typically based on 24V supply.

Magnetic Pickup, MPU (Pins 41 – 42)

The MPU for the MX4-R2 is applied to the magnetic pickup terminals marked 41 MPU- and 42 MPU+, MPU 5-40 Vrms 30-10 kHz. If used, the foil shield and drain wire of the cable assembly may be terminated at 37b- or 38b-. The MPU sends the pulses to the controller, which calculates the engine speed.

FW Murphy recommends using 00031022 Magnetic Pickup 4 in. Length and 00031023 Magnetic Pickup Cable 50 ft.

Important: For Entity Parameters or Power Supply and Grounding, refer to Wire Connections.



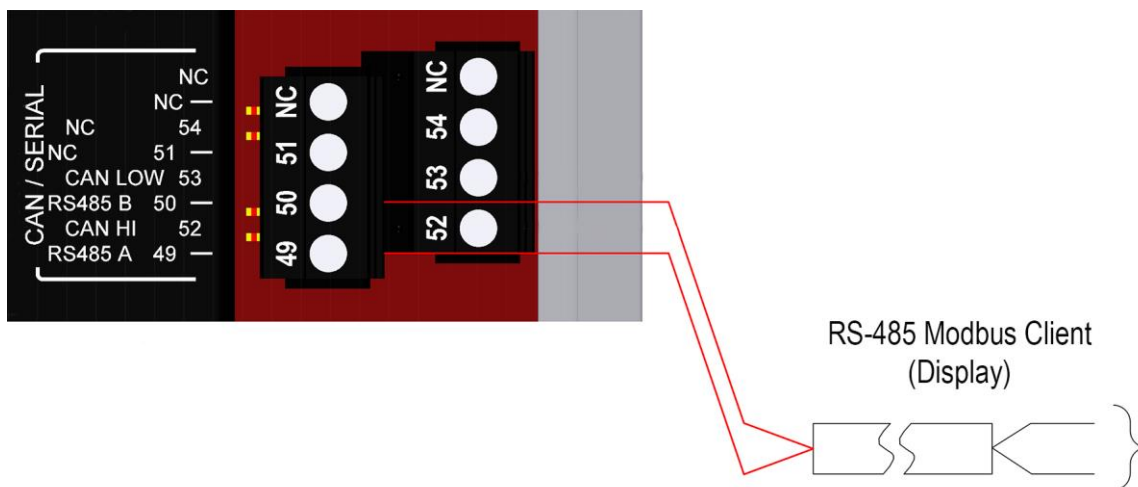
NOTE: The MPU input requires a minimum signal of 2 Vrms when connected.

RS485 (Pins 49 – 50)

The MX4-R2 is equipped with RS485 communications ports 49 A / 50 B.

The TX LED lights when the port is transmitting. The RX LED lights when the port is receiving.

Important: For Entity Parameters or Power Supply and Grounding, refer to Wire Connections.



NOTE: A is the non-inverting pin and should have a single pull-up physically placed anywhere on the network. B is the inverting pin and should have a single pull-down physically placed anywhere on the network.

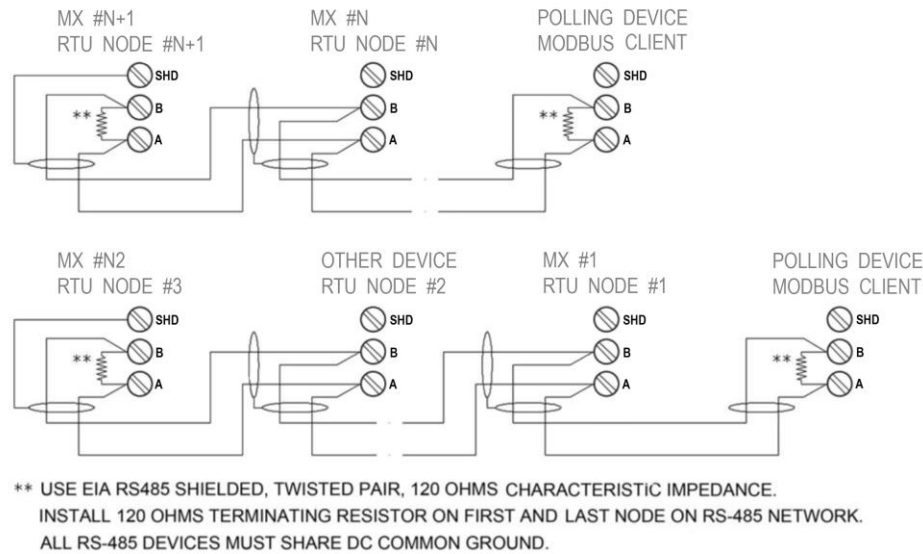
These circuits are not required to be in conduit if all the requirements for ic protection are met and Authority Having Jurisdiction (AHJ) allows.

Consult RS-485 the Murphy Way for information on best practices for connecting and communicating on RS-485.

www.fwmurphy.com/uploaded/documents/pdfs/rs-485murphyway.pdf

The recommended arrangement of the wires is as a connected series of point-to-point (multidropped) nodes, i.e. a line or bus, not a star, ring or multiply connected network.

RS-485 Typical Connections

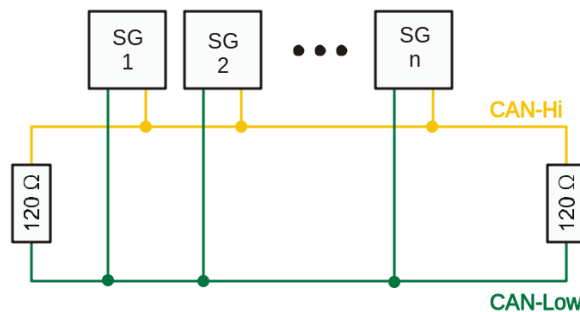


CAN (Pins 52 – 53)

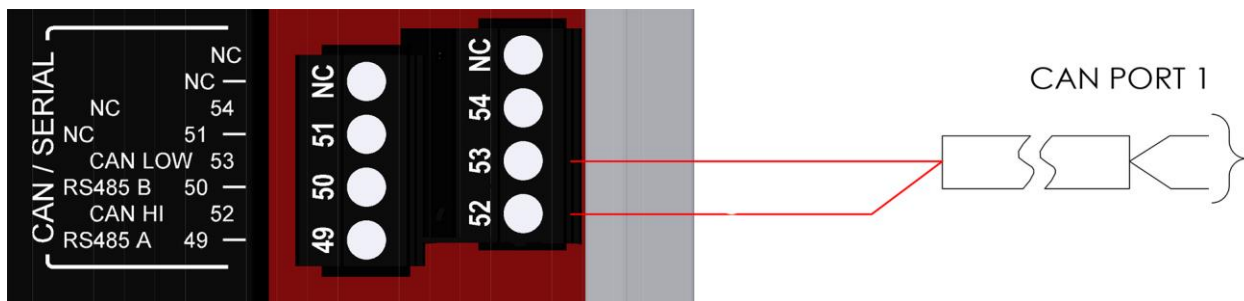
The MX4-R2 is equipped with a CAN communication port. The port is marked pin 52 CAN HI and pin 53 CAN LOW.

The LED lights when the port is active transmitting and when the port is active receiving.

The recommended arrangement of the wires is as a connected series of point-to-point (multidropped) nodes, i.e. a line or bus, not a star, ring or multiply connected network. We recommend using CAN-Bus Cable J1939/11 SAE Shielded, twisted pair with 120 Ω characteristic impedance. Install a 120 Ω terminating resistor (DIP switch controls this on the MX4-R2) on the physical first and last node of the CAN network. All nodes must share a common DC ground



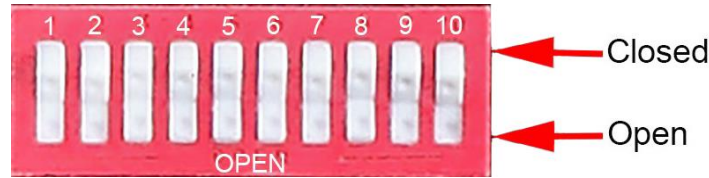
Important: For Entity Parameters or Power Supply and Grounding, refer to Wire Connections.



NOTE: These circuits are not required to be in conduit if all the requirements for ic protection are met and Authority Having Jurisdiction (AHJ) allows.

DIP Switch Configuration

Set these switches to the open or closed position for your application.



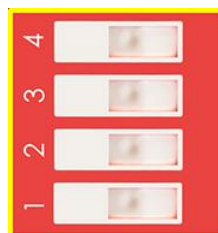
Node Address:

- **DIP1-8:** These switches allow you to assign a unique address to each MX4-R2 that may be in the system using either Modbus or CAN communication. This allows the client controller to differentiate between the modules. Addressing is done in binary format, with each switch increasing value by factor of 2. For example, to name the controller address 5, set switch DIP1 and DIP4 to the CLOSED position. Valid settings are from 1 to 239. Addresses 240 thru 255 are for power-up functions only as detailed below.
- **DIP Power-up Functions:** There is a special feature for switching module operation mode that is activated by setting specific switch positions at power up. Change will only occur if the following switches are set CLOSED at power up. All other times, these switches behave as address selections.
 - DIP switches 5-8 CLOSED at power up activates special mode to change the module behavior based on switches 1-4 position.

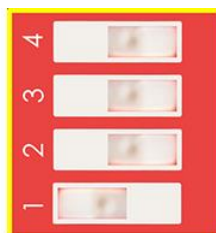


5-8 CLOSED

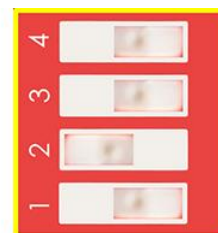
- 1-4 CLOSED: Load factory defaults to non-volatile settings – restores serial baud rate, Ethernet address and channel configurations to default values.
- 1 OPEN, 2-4 CLOSED: Load Rockwell IO Application.
- 2 OPEN, 1, 3, 4 CLOSED: Load Standard IO Application.



1-4 CLOSED



1 OPEN, 2-4 CLOSED



2 OPEN, 1, 3, 4 CLOSED

- **Stop Bits:** For addresses < 31, the RS485 port will use 1 stop bit. For addresses > 31, the RS485 port will use 2 stop bits.

CAN Termination:

- **DIP9:** This switch provides a 120Ω termination resistor for the CAN communication chain. CAN must be wired in a daisy chain configuration. Set this switch to CLOSED only when the module is the end of the network. See control panel drawings for designation.

RS485 Termination:

- **DIP10:** This switch provides a 120Ω termination resistor for the RS485 communication chain. RS485 must be wired in a daisy chain configuration. Set this switch to CLOSED only when the module is the end of the network. See control panel drawings for designation.

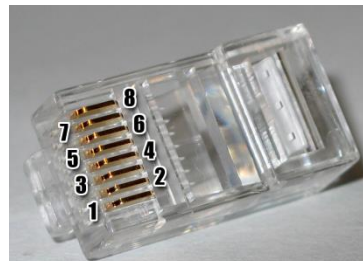
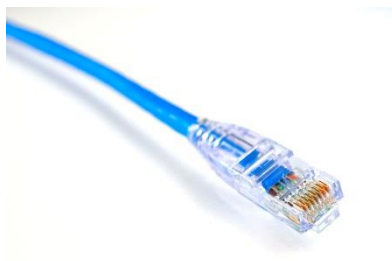
Ethernet

The MX4-R2 is equipped with two Ethernet communication ports. The ports are marked ETHERNET 1 and ETHERNET 2. An LED flashes when the port is active — transmitting or receiving a message, and an LED lights to indicate the link is active when connected to another device. LED closest to the DIP switch illuminates for 100Mbit connections. LED furthest from the DIP switch illuminates for 10Mbit connections.











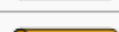







WARNING: Explosion hazard – Do not disconnect the Ethernet port unless the power has been switched off or the area is known to be non-hazardous.

Below is an 8P8C modular connector (often called RJ45) commonly used on Cat 5 cables in Ethernet networks.



Twisted-pair Ethernet standards are such that the majority of cables can be wired "straight-through" (pin 1 to pin 1, pin 2 to pin 2 and so on), but others may need to be wired in the "crossover" form (receive to transmit and transmit to receive). The MX4-R2 can automatically detect another computer connected with a straight-through cable and then automatically introduce the required crossover, if needed with no intervention by the installer. 10BASE-T and 100BASE-TX only require two pairs (pins 1-2, 3-6) to operate. Since Category 5 cable has four pairs, the spare pairs (pins 4–5, 7–8) in 10- and 100-Mbit/s configurations are not used.

TIA/EIA-568 T568A termination				TIA/EIA-568 T568B termination			
Pin	Pair	Wire	Color	Pin	Pair	Wire	Color
1	3	tip	 white/green	1	2	tip	 white/orange
2	3	ring	 green	2	2	ring	 orange
3	2	tip	 white/orange	3	3	tip	 white/green
4	1	ring	 blue	4	1	ring	 blue
5	1	tip	 white/blue	5	1	tip	 white/blue
6	2	ring	 orange	6	3	ring	 green
7	4	tip	 white/brown	7	4	tip	 white/brown
8	4	ring	 brown	8	4	ring	 brown

The MX4-R2 uses autonegotiation, an Ethernet procedure by which two connected devices choose common transmission parameters, such as speed, duplex mode and flow control. In this process, the connected devices first share their capabilities regarding these parameters and then choose the highest performance transmission mode they both support. The MX4-R2 supports 10 and 100 Mbit/s over two-pair Cat5 or better cable.

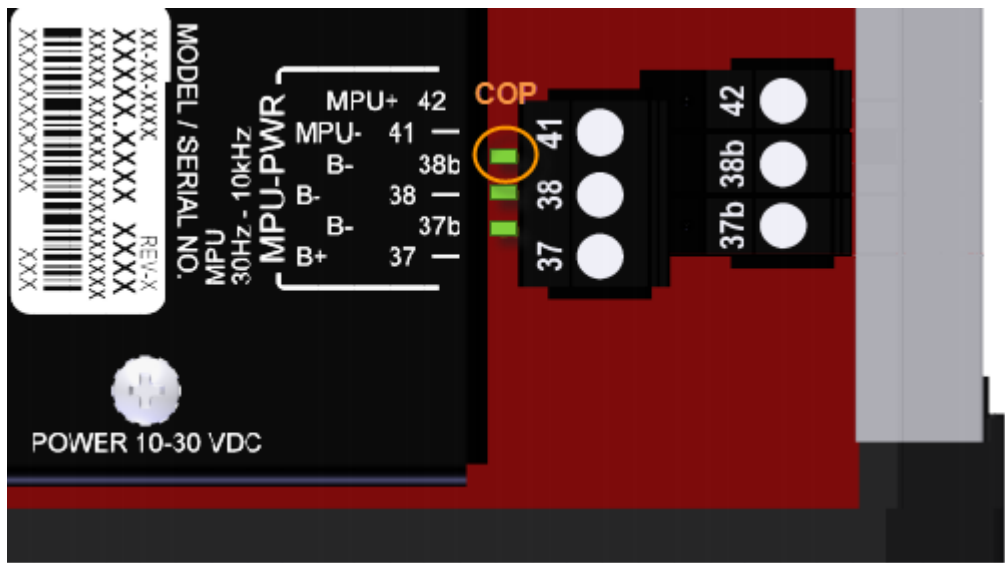
Important: For Entity Parameters or Power Supply and Grounding, refer to Wire Connections.

NOTE: These circuits are not required to be in conduit if all the requirements for ic protection are met and Authority Having Jurisdiction (AHJ) allows.

Controller Operating Properly (COP) LED Codes

Blink codes will be 2 digits separated by pauses with each blink code further separated by a rapid blink event.

- Blink codes will be ¼ second ON and ¼ second OFF.
- Pauses will be ¾ second OFF.
- The separator will be a 2 1/2 seconds pause.



Blink Codes *	Code Description
1, 1	Startup Error
4, 1	Rockwell Automation IO Application Mode
4, 2	Standard IO Application Mode
4, 3	Custom Application Mode
* There will be a ¾ second pause between the digits.	

NOTE: A fast flash (100ms on/off) = Running in bootloader mode. Bootloader is the mode used for switching applications or module reprogramming via external CAN tools.

Communications for Standard IO Application Mode (default)

Physical Layer: The MX4-R2 module features two Ethernet ports, one RS485 serial communication port and one CAN bus 2.0B communication port.

Ethernet Interconnect: Two RJ45 jacks with single MAC ID. This connection may require setting the IP address of the module to the desired network configuration. Ethernet port settings can be changed by modifying Modbus registers. Default setting is 192.168.0.100 IP, 255.255.255.0 network mask, 0.0.0.0 Gateway.

Ethernet Protocol: Modbus TCP/IP server. Refer to the Modbus RTU map provided in this manual for a detailed mapping of the available data and data scaling.

Serial RS485 Interconnect: Screw terminals. Typically, this connection uses twisted shielded pair cable with 120-ohm impedance. RS485 networks are 2-wire, half-duplex and feature an “A” terminal 49 and “B” terminal 50. The A terminal is the + or non-inverting signal, and the B terminal is the – or inverting signal. These signal lines will take turns transmitting and receiving depending on the device using the RS485 network at any given instant.

Serial Baud Rate: Default 9600, adjustable up to 115.2k.

Serial Stop Bits: The module will respond with 1 stop bit for Modbus RTU addresses 1 through 31 and 2 stop bits for addresses 32 through 239. This maintains flexibility for systems requiring 2 stop bits.

Serial Protocol: Modbus RTU server. The module may be polled by the Modbus RTU Client without any additional timing delays and response times will be < 100mS. This may vary depending on the amount of data requested. Modbus RTU timeout settings should be set to >= 400mS.

Refer to the Modbus RTU map provided in this manual for a detailed mapping of the available data and data scaling.

CAN bus Interconnect: Screw terminals. Typically, this connection uses twisted pair cable with 120-ohm impedance to connect to a FW Murphy Controller. CAN bus networks are 2-wire with a “HI” terminal 52 and “LOW” terminal 53.

CAN bus Baud Rate: 250kbit/500kbit/1000kbit auto sense.

CAN bus Protocol: Proprietary for FW Murphy Controllers.

PC Connection: Reading data from the module into a PC may be done with an Ethernet connection and Modbus TCP/IP client software or RS485 connection and Modbus RTU client software. A serial interface converter that can convert USB to RS485 would be needed for a serial connection. (FW Murphy MConfig™ Software and P/N 53702325 may be used for this purpose.)

Communications for Rockwell Automation IO Mode

Physical Layer: The MX4-R2 module features two Ethernet ports.

Ethernet Interconnect: Two RJ45 jacks with Single MAC ID. This connection may require setting the IP address of the module to the desired network configuration. Ethernet port settings can be changed by modifying Modbus registers. Default setting is 192.168.0.100 IP, 255.255.255.0 network mask, 0.0.0.0 Gateway.

Ethernet Protocol: CIP for use with Rockwell Automation IO.

Modbus Holding Register Description (Standard IO Application Mode)

All data will be contained in 16-bit Modbus Holding Registers. Following the Modbus RTU and Modbus TCP/IP specification, the Most Significant Byte in a 16-bit word is broadcast first, followed by the Least Significant Byte. The module responds to Modbus Function Code 03 (Read Holding Registers), Function Code 06 (Preset Single Holding Register) and Function Code 16 (Preset Multiple Holding Register). Polling invalid/non-existent data will result in Modbus Exception Code response from the module.

Modbus Holding Register Description Used With Standard IO Application Mode					
Modbus Register	Description	Read/Write	Data Range	Data Units	Definitions / Sample Data
400001	Hardware Type	R	32	ID	Module name
400002 – 400004	Factory Use	R			
400005	Bootloader Build Version	R	0 – 65535		Version number
400006	Not Used	R			
400007	Firmware Number	R	0 – 65535		Version number
400008	Firmware Build Version	R	0 – 65535		Version number
400009	Firmware Checksum MSW	R	0 – 65535		
400010	Firmware Checksum LSW	R	0 – 65535		
400011	Firmware Major Version	R	0 – 65535		Version number
400012	Firmware Minor Version	R	0 – 65535		Version number
400013	Bootloader Major Version	R	0 – 65535		Version number
400014	Bootloader Minor Version	R	0 – 65535		Version number
400015 – 400020	Factory Use	R			
400021	System Voltage	R	0-65535	Vdc x10	0 = 0.0 VDC, 320 = 32.0 VDC
400022	Raw Channel 1	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400023	Raw Channel 2	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400024	Raw Channel 3	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400025	Raw Channel 4	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400026	Raw Channel 5	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400027	Raw Channel 6	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400028	Raw Channel 7	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400029	Raw Channel 8	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400030	Raw Channel 9	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400031	Raw Channel 10	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400032	Raw Channel 11	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400033	Raw Channel 12	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400034	Raw Channel 13	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400035	Raw Channel 14	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV

Modbus Holding Register Description Used With Standard IO Application Mode					
Modbus Register	Description	Read/Write	Data Range	Data Units	Definitions / Sample Data
400036	Raw Channel 15	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400037	Raw Channel 16	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400038	Raw Channel 17	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400039	Raw Channel 18	R	-32767 – 32768	mV x100	0 = 0.00 mV, 7500 = 75.00 mV
400040	Raw Cold Junction Input	R	0 – 65535	A/D count	
400041	Not Used	R			
400042	Frequency input	R	0 – 10,000	Hz	
400043	Factory Use	R			
400044	Not Used	R			
400045	Filtered Temperature Channel 1	R	-2000 to +25000	deg F X10	
400046	Filtered Temperature Channel 2	R	-2000 to +25000	deg F X10	
400047	Filtered Temperature Channel 3	R	-2000 to +25000	deg F X10	
400048	Filtered Temperature Channel 4	R	-2000 to +25000	deg F X10	
400049	Filtered Temperature Channel 5	R	-2000 to +25000	deg F X10	
400050	Filtered Temperature Channel 6	R	-2000 to +25000	deg F X10	
400051	Filtered Temperature Channel 7	R	-2000 to +25000	deg F X10	
400052	Filtered Temperature Channel 8	R	-2000 to +25000	deg F X10	
400053	Filtered Temperature Channel 9	R	-2000 to +25000	deg F X10	
400054	Filtered Temperature Channel 10	R	-2000 to +25000	deg F X10	
400055	Filtered Temperature Channel 11	R	-2000 to +25000	deg F X10	
400056	Filtered Temperature Channel 12	R	-2000 to +25000	deg F X10	
400057	Filtered Temperature Channel 13	R	-2000 to +25000	deg F X10	
400058	Filtered Temperature Channel 14	R	-2000 to +25000	deg F X10	
400059	Filtered Temperature Channel 15	R	-2000 to +25000	deg F X10	
400060	Filtered Temperature Channel 16	R	-2000 to +25000	deg F X10	
400061	Filtered Temperature Channel 17	R	-2000 to +25000	deg F X10	
400062	Filtered Temperature Channel 18	R	-2000 to +25000	deg F X10	
400063	Cold Junction Temperature	R	-400 to +1850 F	deg F X10	
400064	Factory Use	R			
400065	Factory Use	R			
400066	Factory Use	R			
400067	Unfiltered Temperature Channel 1	R	-2000 to +25000	deg F X10	
400068	Unfiltered Temperature Channel 2	R	-2000 to +25000	deg F X10	
400069	Unfiltered Temperature Channel 3	R	-2000 to +25000	deg F X10	
400070	Unfiltered Temperature Channel 4	R	-2000 to +25000	deg F X10	
400071	Unfiltered Temperature Channel 5	R	-2000 to +25000	deg F X10	

Modbus Holding Register Description Used With Standard IO Application Mode					
Modbus Register	Description	Read/Write	Data Range	Data Units	Definitions / Sample Data
400072	Unfiltered Temperature Channel 6	R	-2000 to +25000	deg F X10	
400073	Unfiltered Temperature Channel 7	R	-2000 to +25000	deg F X10	
400074	Unfiltered Temperature Channel 8	R	-2000 to +25000	deg F X10	
400075	Unfiltered Temperature Channel 9	R	-2000 to +25000	deg F X10	
400076	Unfiltered Temperature Channel 10	R	-2000 to +25000	deg F X10	
400077	Unfiltered Temperature Channel 11	R	-2000 to +25000	deg F X10	
400078	Unfiltered Temperature Channel 12	R	-2000 to +25000	deg F X10	
400079	Unfiltered Temperature Channel 13	R	-2000 to +25000	deg F X10	
400080	Unfiltered Temperature Channel 14	R	-2000 to +25000	deg F X10	
400081	Unfiltered Temperature Channel 15	R	-2000 to +25000	deg F X10	
400082	Unfiltered Temperature Channel 16	R	-2000 to +25000	deg F X10	
400083	Unfiltered Temperature Channel 17	R	-2000 to +25000	deg F X10	
400084	Unfiltered Temperature Channel 18	R	-2000 to +25000	deg F X10	
400085 - 400087	Factory Use	R			
400088	Channel 1 type	R/W	0 - 9	0 = J, 1 = K, 2 = 100Ω Pt RTD, 8 = J Strict, 9 = k Strict	Strict option enables advanced wire fault detection for DC-/DC+ mV leak/temperature shift.
400089	Channel 2 type	R/W	0 - 9	0 = J, 1 = K, 8 = J Strict, 9 = k Strict	
400090	Channel 3 type	R/W	0 - 9	0 = J, 1 = K, 2 = 100Ω Pt RTD, 8 = J Strict, 9 = k Strict	
400091	Channel 4 type	R/W	0 - 9	0 = J, 1 = K, 8 = J Strict, 9 = k Strict	
400092	Channel 5 type	R/W	0 - 9	0 = J, 1 = K, 2 = 100Ω Pt RTD, 8 = J Strict, 9 = k Strict	
400093	Channel 6 type	R/W	0 - 9	0 = J, 1 = K, 8 = J Strict, 9 = k Strict	
400094	Channel 7 type	R/W	0 - 9	0 = J, 1 = K, 2 = 100Ω Pt RTD, 8 = J Strict, 9 = k Strict	
400095	Channel 8 type	R/W	0 - 9	0 = J, 1 = K, 8 = J Strict, 9 = k Strict	
400096	Channel 9 type	R/W	0 - 9	0 = J, 1 = K, 2 = 100Ω Pt RTD, 8 = J Strict, 9 = k Strict	
400097	Channel 10 type	R/W	0 - 9	0 = J, 1 = K, 8 = J Strict, 9 = k Strict	
400098	Channel 11 type	R/W	0 - 9	0 = J, 1 = K, 2 = 100Ω Pt RTD, 8 = J Strict, 9 = k Strict	

Modbus Holding Register Description Used With Standard IO Application Mode					
Modbus Register	Description	Read/Write	Data Range	Data Units	Definitions / Sample Data
400099	Channel 12 type	R/W	0 – 9	0 = J, 1 = K, 8 = J Strict, 9 = k Strict	
400100	Channel 13 type	R/W	0 - 9	0 = J, 1 = K, 2 = 100Ω Pt RTD, 8 = J Strict, 9 = k Strict	
400101	Channel 14 type	R/W	0 – 9	0 = J, 1 = K, 8 = J Strict, 9 = k Strict	
400102	Channel 15 type	R/W	0 - 9	0 = J, 1 = K, 2 = 100Ω Pt RTD, 8 = J Strict, 9 = k Strict	
400103	Channel 16 type	R/W	0 – 9	0 = J, 1 = K, 8 = J Strict, 9 = k Strict	
400104	Channel 17 type	R/W	0 - 9	0 = J, 1 = K, 2 = 100Ω Pt RTD, 8 = J Strict, 9 = k Strict	
400105	Channel 18 type	R/W	0 – 9	0 = J, 1 = K, 8 = J Strict, 9 = k Strict	
400106	Cold junction offset	R/W	-32768 to +32767	deg F	Modify this value to offset the cold junction reading
400107	Not Used	R			
400108	Not Used	R			
400109	Communication Timeout	R/W	0 – 65535	time in seconds	
400110	Serial Port Baud Rate	R/W	1-5	Enumeration	1=9600, 2=19.2k, 3=38.4k, 4=57.6k, 5=115.2k
400111-400140	Factory Use	R			
400141	Channel 1 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400142	Channel 2 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400143	Channel 3 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400144	Channel 4 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400145	Channel 5 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+

Modbus Holding Register Description Used With Standard IO Application Mode					
Modbus Register	Description	Read/Write	Data Range	Data Units	Definitions / Sample Data
400146	Channel 6 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400147	Channel 7 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400148	Channel 8 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400149	Channel 9 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400150	Channel 10 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400151	Channel 11 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400152	Channel 12 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400153	Channel 13 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400154	Channel 14 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400155	Channel 15 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400156	Channel 16 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
400157	Channel 17 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+

Modbus Holding Register Description Used With Standard IO Application Mode					
Modbus Register	Description	Read/Write	Data Range	Data Units	Definitions / Sample Data
400158	Channel 18 Status	R	1 –7	enumeration	1 = TC OK, 2 = RTD OK, 3 = OPEN, 4 = MINOR SHORT DC-, 5= MAJOR SHORT DC-, 6 = MINOR SHORT DC+, 7 = MAJOR SHORT DC+
465197	IP Address Part 1	R/W	0-255	octet	Ethernet setting
465198	IP Address Part 2	R/W	0-255	octet	Ethernet setting
465199	IP Address Part 3	R/W	0-255	octet	Ethernet setting
465200	IP Address Part 4	R/W	0-255	octet	Ethernet setting
465201	Network Mask Part 1	R/W	0-255	octet	Ethernet setting
465202	Network Mask Part 2	R/W	0-255	octet	Ethernet setting
465203	Network Mask Part 3	R/W	0-255	octet	Ethernet setting
465204	Network Mask Part 4	R/W	0-255	octet	Ethernet setting
465205	Gateway Address Part 1	R/W	0-255	octet	Ethernet setting
465206	Gateway Address Part 2	R/W	0-255	octet	Ethernet setting
465207	Gateway Address Part 3	R/W	0-255	octet	Ethernet setting
465208	Gateway Address Part 4	R/W	0-255	octet	Ethernet setting
465209	DNS1 Address Part 1	R/W	0-255	octet	Ethernet setting
465210	DNS1 Address Part 2	R/W	0-255	octet	Ethernet setting
465211	DNS1 Address Part 3	R/W	0-255	octet	Ethernet setting
465212	DNS1 Address Part 4	R/W	0-255	octet	Ethernet setting
465213	DNS2 Address Part 1	R/W	0-255	octet	Ethernet setting
465214	DNS2 Address Part 2	R/W	0-255	octet	Ethernet setting
465215	DNS2 Address Part 3	R/W	0-255	octet	Ethernet setting
465216	DNS2 Address Part 4	R/W	0-255	octet	Ethernet setting
465217	Ethernet IP Options	R/W	0-4	Bitmap	0=static ip / no auto IP 1= DHCP enabled / no auto IP 2 = static ip / use Auto IP if no DHCP or IP 3 = DHCP enabled / use Auto IP if no DCHP or IP
465218	MAC Address word 1	R	0 – 65535		
465219	MAC Address word 2	R	0 – 65535		
465220	MAC Address word 3	R	0 – 65535		

Register 400001 Value Description

Register 400001 is a read-only register. This register holds the model number of the hardware. If you are using multiple Comm modules, it is sometimes helpful to confirm that you are communicating with the expected module type. In this case, it will return 32.

Unfiltered Temperature Readings (400045 – 400064)

Registers 400045 – 400064 are read-only registers. The values returned in these registers are signed 16-bit data. These channels are the actual readings from the connected sensor. Channels are shown in degrees F x 10. For example, a read value of 1200 means 120°F is being read.

NOTE: These values are not averaged. The device reading these values may need additional software filtering to remove noise in the readings.

Filtered Temperature Readings (400067 – 400084)

Registers 400067 – 400084 are read-only registers. The values returned in these registers are signed 16-bit data. These channels are filtered internally with a median value of 3 samples and then running average of last 4 readings. This will require approximately 400ms for an accurate reading on initial powerup. Thermocouple channels are shown in deg F x 10. For example, a read value of 1200 means 120°F is being read.

NOTE: These values are generally more desirable to use by a controller. Software filtering has been internally applied by the module and no additional filtering is necessary by the controller.

Channel Type (400088 – 400105)

Registers 400088 – 400105 are read/write registers. This will allow you to configure what type of sensor is attached to each channel. *Only odd-numbered channels may be configured as RTD type. When configured as RTD, the adjacent even-numbered channel is not available for use, and the type data will be ignored. Use the list below to determine what value you should write based on the sensor installed.

- 0 – Type J thermocouple
- 1 – Type K thermocouple
- 2 – 100Ω Pt 3-wire RTD
- 8 – *Type J thermocouple with advanced (strict) wire fault detection enabled.
- 9 – *Type K thermocouple with advanced (strict) wire fault detection enabled
- *Applies to firmware version 3.1.10113 or higher.

Channel Status (400141 – 400158)

Registers 400141 – 400158 are read-only registers. The values between 1-7 show channel status. The MX4-R2 can detect shorts to DC-, shorts to DC+ and open circuit for the thermocouple and RTD wiring.

It also detects leaking current to DC- or DC+ which will start causing errors in readings. This is generally due to breakdown of insulation. As this condition worsens, the status may change to indicate a short.

Notes

This image shows a single sheet of white paper with horizontal ruling lines. The lines are evenly spaced and run across the width of the page. There are no margins, text, or other markings on the paper.

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